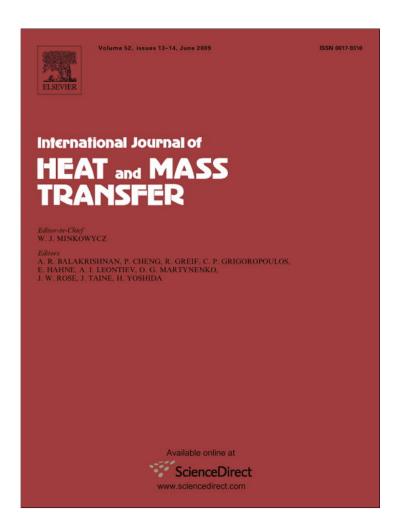
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A study of the Sherwood–Rayleigh relation for water undergoing natural convection-driven evaporation

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ABSTRACT

An experimental study is presented of evaporative free-surface natural convection. A power law relationship is developed between the Sherwood number for evaporation (Sh) and the Rayleigh number for air-side natural convection (Ra). Evaporation of water was investigated in sixteen different tanks having four depths and four widths. Evaporation rates and the relevant temperatures and relative humidity were measured, from which the air-side Sherwood and Rayleigh numbers were obtained. The resulting power law is $Sh \sim Ra^{0.321}$. This power law is compared to those obtained by other researchers. A brief discussion of the possible effect of water-side natural convection on evaporation is also presented.

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1. Introduction

Demands on freshwater supplies for industrial, agricultural and human needs make important the ability to predict evaporation rates from inland bodies of water such as reservoirs and lakes [1–4], ponds [5], cooling impoundments [6], swimming pools [7], and livestock ponds [8]. The focus of the present study is evaporation from a water surface where natural convection is the dominant transport mechanism. Such a situation is not uncommon when wind speeds are small.

Field studies of evaporation from inland water bodies comprise a large body of literature. These studies, almost exclusively, seek to predict evaporation rates using equations of the form:

$$\dot{m}'' = f(\bar{u})(e_s - e_\infty) \tag{1}$$

where \dot{m}'' is the evaporation rate, $f(\bar{u})$ is a function of the mean wind speed \bar{u}, e_s is the saturation vapor pressure at the water surface temperature, and e_∞ is the vapor pressure in the air [9]. Other environmental parameters, such as lake size, are often included in Eq. (1). Field studies typically seek to fit data to a wind speed function $f(\bar{u})$ having the form:

$$f(\bar{u}) = a + b\bar{u} \tag{2}$$

originally suggested by Penman [10], where a and b are fitting constants, obtained from the field data. Some examples of field studies which yield equations of the form presented in Eq. (1) are Kohler and Parmele [1] who give:

$$\dot{m}'' = \rho(0.181 + 0.00236\bar{u})(e_s - e_{\infty}) \tag{3}$$

where ρ is the liquid water density¹ and Taga et al. [11], who found:

$$\dot{m}'' = (0.088403 + 0.001296\bar{u})(e_s - \gamma e_\infty)/h_{fg} \tag{4}$$

where γ is the relative humidity, and h_{fg} is the latent heat of vaporization for water. Space limitations preclude a detailed survey of the literature, and good surveys can be found in the work of Sartori [12], Sweers [13], and Warnaka and Pochop [2].

A drawback of parameterizing the evaporation rate using Eqs. (1) and (2) is that not all of the known processes that affect evaporation are included. For example, a and b are known to vary with climate, season, solar conditions, geographical location, lake size, etc. [12,13]. Hence the results of field studies like those cited above tend to lose their utility when the equations are applied to other lakes or different conditions. Although this approach is necessary in the interim to provide some level of predictive capability, a long-term goal should be to obtain an understanding of each of the physical processes that affect lake evaporation.

One such process is natural convection, which is the motivation for the present study. According to the form of the wind speed function in Eq. (2) when $\bar{u}=0$, $f(\bar{u})=a$ which, from Eq. (1) gives a linear relationship between the evaporation rate and the driving vapor pressure difference, viz. the mass transfer coefficient (h_m , defined below) is a constant. Hence, equations of this form cannot predict the effect of natural convection on evaporation.

For small inland water bodies, conditions of low wind speed, where natural convection dominates, are not uncommon. For

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¹ Note that the units used in Eq. (3) are not SI, as is the case for all other equations in this paper

Nomenclature surface area (m2) wind speed (m/s) Α и Sh-Ra power law prefactor W tank width (m) В C Nu-Ra power law prefactor D tank depth (m) Greek symbols D diffusion coefficient (m²/s) thermal diffusivity of liquid water (m²/s) е water vapor pressure (N/m²) coefficient of volumetric expansion (K⁻¹) β gravitational acceleration (m/s²) relative humidity (%) g γ h heat transfer coefficient (W/m² K) kinematic viscosity (m²/s) ν h_{fg} latent heat of vaporization for water (kJ/kg) ρ density (kg/m³) mass transfer coefficient (m/s) h_m k thermal conductivity (W/m K) Subscripts L^* characteristic length, A/P (m) Nu-Ra power law exponent m bulk water, or beaker h 'n′ mass flux $(kg/m^2 s)$ ambient ∞ Sh-Ra power law exponent n S surface Nu Nusselt number saturation sat tank perimeter (m) P tank Ra Rayleigh number tot total Schmidt number Sc water vapor Sh Sherwood number T temperature (°C)

example a 10 year study of wind speed over Lake Sparkling in northern Wisconsin showed that the average wind speed during the summer was 2.3 m/s [14]. For the southeastern portion of the U.S. the average wind speed is less than 3 m/s for half of the year and the same is true for most of the continental U.S. for the months of June, July and August [15]. Similar results have been reported in the United Kingdom [16]. A long duration measurement campaign over a pond at the DOE Savannah River Site (SRS) in Aiken, South Carolina shows a peak in the wind speed probability density function at u < 2 m/s [17].

While the need to predict evaporation rates under natural convection dominated conditions exists, the body of literature on this subject is relatively limited. This literature consists of laboratory studies wherein a dimensionless mass transfer coefficient for evaporation, the Sherwood number, is related to natural convection through the Rayleigh number using a power law of the form:

$$Sh \sim Ra^n$$
 (5)

where Sh is the Sherwood number, defined as:

$$Sh = \frac{h_m W}{\mathscr{D}} \tag{6}$$

and W is the characteristic length (a horizontal dimension in this study), and \mathscr{D} is the diffusion coefficient for water vapor in air. The mass transfer coefficient for evaporation, h_m is:

$$h_m = \dot{m}'' / \Delta \rho_{wv} \tag{7}$$

where:

$$\Delta \rho_{wv} = \rho_{wv,s} - \gamma \rho_{wv,\infty} \tag{8}$$

Here, $\rho_{wv,s}$ and $\rho_{wv,\infty}$ are the saturated vapor densities evaluated at the water surface temperature T_s and ambient air temperature T_∞ , respectively, and γ is the relative humidity in the ambient. The Rayleigh number, Ra, is defined as:

$$Ra = \frac{g\Delta\rho W^3}{\bar{\rho}_{VQ}} \tag{9}$$

where, g is the gravitational acceleration, v and α are the kinematic viscosity and thermal diffusivity or air, respectively, and:

$$\Delta \rho = \rho_{\infty} - \rho_{\rm s} \tag{10}$$

where ρ_s and ρ_{∞} are the air/vapor mixture densities at the water surface and ambient, respectively, and $\bar{\rho}$ is the average of ρ_s and ρ_{∞} .

A total of five studies were found which relate *Sh* to *Ra* for natural convection conditions. Sparrow et al. [18] studied evaporation using a series of water-filled pans in a 70 m³ cork-lined room. Pans having diameters ranging from 8.89 cm to 30.68 cm were studied. For the case where the water level was flush with the tank rim (the condition closest to that used in the present study, where the meniscus was slightly above the tank rim), Sparrow et al. [18] found:

$$Sh = 0.764Sc^{1/3}Ra^{0.205} (11)$$

where Sc is the Schmidt number, defined as:

$$Sc = \frac{v}{\mathscr{D}}. (12)$$

We note that in the actual work of Sparrow et al. [18], the Schmidt number dependence is ignored. That is, the term $Sc^{1/3}$ does not appear and is implicitly included in the prefactor. Here, and in the presentation of subsequent literature, we have rewritten the Sh-Ra relationships developed by each author in the form:

$$Sh = BSc^{1/3}Ra^n (13)$$

to enable comparison of the prefactors from different studies where different working fluids were used.

A unique aspect of the work of Sparrow et al. [18] was that for all of their experimental runs, the water temperature was less than the air temperature, resulting in a buoyancy-driven downflow. That is, the air/vapor mixture moved from the ambient towards the water. In the experiments presented herein, the water temperature was greater than the ambient, resulting in an upflow.

Sharpley and Boelter [19] and Boelter et al. [20], both using the same experimental facility, investigated evaporation of heated water from a pan into a 'quiet air apparatus.' Specifically, a one foot diameter pan was placed in a $5 \times 5 \times 7$ foot chamber, with vents connecting the chamber to the laboratory air. The resulting Sh-Ra relationship is:

$$Sh = 4.687Sc^{1/3}Ra^{0.121} (14)$$

for Boelter et al. [20] and

$$Sh = 1.254Sc^{1/3}Ra^{0.213} (15)$$

for Sharpley and Boelter [19]. Due to slight differences in the definitions of the relevant dimensionless groups from those used here, Eqs. (14) and (15) were obtained by reprocessing the actual data presented in Boelter et al. [20] and Sharpley and Boelter [19] to conform to the definitions of Sh and Ra used here. It should also be noted that the Sharpley and Boelter [19] data set included very small as well as negative values of Ra; at times the water surface temperature was less than the ambient. These data were excluded when developing Eq. (15).

Goldstein et al. [21] investigated the sublimation of naphthalene from planforms of square, rectangular and circular shape into a quiescent air environment having a volume of 110 m³. Although sublimation differs from evaporation in that the interfacial hydrodynamic boundary condition is no-slip, there is nevertheless a similarity in that this study still investigates mass transfer due solely to natural convection. The *Sh–Ra* relation that they obtained was:

$$Sh = 0.435Sc^{1/3}Ra^{0.250} (16)$$

In order to collapse their (Sh, Ra) data obtained from different geometry planforms, Goldstein et al. [21] employed the length scale,

$$L^* = A/P \tag{17}$$

in their definition of Sh and Ra, where A is the planform surface area and P is the perimeter.

Lloyd and Moran [22] studied mass transfer in the presence of natural convection using an electrochemical method. This electrochemical method created a density difference above a horizontal copper plate in a solution H_2SO_4 and $CuSO_4$, and Cu^{2+} ions were the quantity transported. As in the work of Goldstein et al. [21], Lloyd and Moran [22] used L^* as their characteristic length. The resulting Sh-Ra relation was:

$$Sh = 0.038Sc^{1/3}Ra^{0.255} (18)$$

for the laminar regime where $2.2 \times 10^4 < Ra < 8.0 \times 10^6$, and

$$Sh = 0.013Sc^{1/3}Ra^{0.327} (19)$$

for the turbulent regime where $8.0 \times 10^6 < Ra < 1.6 \times 10^9$. As for the case of Goldstein et al. [21], this study differs from actual evaporative transport in the existence of a no-slip boundary condition at the mass transfer interface.

The five studies cited above are compiled in tabular form in Table 1, with each Sh—Ra relationship rewritten in the form of Eq. (13).

The above survey of the literature reveals that a large amount of work has been done which attempts to parameterize the

Table 1 Comparison of Sh-Ra power law prefactors and exponents from the present work and earlier studies. Note that for the results presented in lines 6–8, the length scale used is L^* (Eq. (17)). To facilitate comparison with these three studies, the present work has been reformulated using this length scale in line 5.

Parameterization	$Sh = BSc^{1/3}Ra^n$			
	В	n	Sc	Ra range
1. Present study	0.230	0.321	0.60	$9.6 \times 10^5 < \textit{Ra} < 5.7 \times 10^8$
2. Sharpley and Boelter [19]	1.057	0.213	0.60	$10^6 < Ra < 4.5 \times 10^7$
3. Boelter et al. [20]	0.645	0.241	0.60	$9.3 \times 10^6 < Ra < 4.6 \times 10^8$
4. Sparrow et al. [18]	0.764	0.205	0.60	$-6 \times 10^5 < Ra < -2 \times 10^4$
5. Present study (using L^*)	0.196	0.322	0.60	$2 \times 10^4 < Ra_{L^*} < 9 \times 10^6$
6. Goldstein et al. [21]	0.435	0.250	2.5	$2 \times 10^2 < Ra_{L^*} < 5 \times 10^3$
7. Lloyd and Moran [22]	0.013	0.327	2200	$8 \times 10^6 < Ra_{L^*} < 1.6 \times 10^9$
8. Lloyd and Moran [22]	0.038	0.255	2200	$2 \times 10^4 < Ra_{L^*} < 8 \times 10^6$

evaporation rate on lakes and other inland water bodies to wind speed, as well as other factors. However, we have been able to identify only five studies which quantify mass transfer under purely natural convection conditions. One of the motivations of the present study is to expand on this relatively small body of research. Additionally, of the five studies cited above, only three actually pertained to the evaporative transport of water. Of these three citations, the work of Sparrow et al. [18] pertains only to conditions where the water is colder than the air, resulting in a density gradient that drives a downflow in the air, the opposite of what would typically occur on heated water bodies. Finally, in the work of Boelter et al. [20] and Sharpley and Boelter [19], the flow of air was restricted by the close proximity of the evaporation pan to the wall of the quieting chamber, as well as by vertical baffles which were introduced to reduce air motion. Those authors noted that these restrictions significantly changed the evaporation rate. It seems then, that a study of the Sh-Ra relationship has not been conducted for evaporation from a water body where the air flow is relatively unrestricted, a situation more like that which occurs on a pond undergoing pure natural convection. The absence of such a study is the second motivation for the work presented here.

2. Experimental method

Experiments were conducted using a set of insulated glass tanks, all of which were different in either depth or width. The tanks were filled with warm tap water and allowed to cool down in a quiescent laboratory environment for 1-2 h while data were collected. The measurements included: the bulk water temperature, T_b , the surface temperature of the water, T_s , the room air temperature, T_s , the room relative humidity, γ , and the mass loss due to evaporation, \dot{m}'' . From these data, Sh and Ra were calculated and power law fits were subsequently generated. A schematic of the experimental apparatus is shown in Fig. 1.

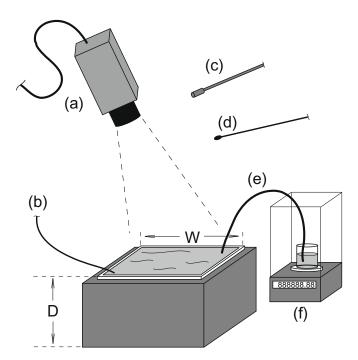


Fig. 1. Diagram of the experimental facility showing an insulated tank of width, W, and depth, D, (a) infrared camera for surface temperature measurements, (b) water bulk temperature sensor, (c) relative humidity probe, (d) air temperature probe, (e) water siphon tube, and (f) electronic balance for evaporation measurement.

The bulk water temperature was measured with a Fluke 5611T thermistor (± 0.01 °C) and the air temperature was measured with a General Electric CSP60BA103M-H/2-90 thermistor (± 0.01 °C). These data were logged with a Hart Scientific 1529 Chub-E4 Thermometer Readout (±0.002 °C accuracy and 0.0001 °C resolution). The surface temperature was measured by processing digital imagery taken with an Inframetrics Thermacam SC1000 infrared camera $(\pm 0.07~\text{K})$ with a platinum silicide 255 \times 239 focal plane array sensor, sensitive to infrared light in the 3.4–5 µm wavelength band. Prior to the experiments, the camera was calibrated with an Infrared Systems Development Corporation model IR-140/301 Blackbody Source (emissivity of $0.96 \pm 0.02\%$) and Controller System $(\pm 0.2 \, \text{K} \text{ accuracy and } 0.1 \, \text{K} \text{ resolution})$. For measuring the room relative humidity, γ , a Digi-Sense Thermohygrometer data logger and probe were used (0.1% relative humidity resolution and accuracy of $\pm 0.2\%$ of reading). Mass was measured using a Scientech Zeta Series ZSA210 electronic balance (± 0.15 mg accuracy, ± 0.2 mg linearity and 0.1 mg resolution).

The water tanks were made of 9.5 mm thick glass and silicone RTV (type 110) adhesive and were constructed with depths of 5.1, 10.2, 15.2, and 35.5 cm and widths of 15.2, 30.5, 45.7, and 60.9 cm. All tank footprints were square. All combinations of these depths and widths were explored, resulting in a total of 16 tanks. Two layers of 1.9 cm thick Perma "R" expanded polystyrene panel foam were used to insulate the sides and bottom of each tank to minimize heat loss through the tank walls.

Each tank was filled with tap water at approximately 43 °C such that the interface was pinned at the tank rim and the meniscus was slightly above the rim. The T_b thermocouple was located at tank mid-depth. It is assumed that the tank fluid is well-mixed by natural convection, and hence that T_b is representative of the bulk fluid temperature. The T_∞ thermocouple and the relative humidity probe were placed sufficiently far from the tank setup to not disturb air flow at the water surface. The distance from the IR camera lens to the water surface was 46 cm, and the camera was mounted approximately 25° from vertical.

The evaporative mass loss was measured by running a flexible siphon tube (91 cm in length, 4.5 mm in diameter) from the tank to a small beaker of water located on the weighing pan inside the balance enclosure. Thus, as water from the tank evaporated, water flowed through the siphon tube from the beaker into the tank, resulting in a decrease in the mass measured by the balance. Measures were taken to increase the relative humidity of the environment within the balance enclosure in order to prevent significant evaporation of water from the beaker. Nevertheless, finite evaporation occurred and a separate set of experiments were performed to correct for this, in which the siphon tube was disconnected and the beaker evaporation was recorded. This beaker evaporation rate was subtracted from the measured evaporation rate for each experimental run. Upon filling the tank with water, the system was allowed to sit for 1 h prior to acquiring data.

The mass flux from the tank, \dot{m}'' , was obtained from:

$$\dot{m}'' = \frac{(dm/dt)_b}{A_b} = \frac{(dm/dt)_t}{A_t} \tag{20}$$

where A_b and A_t are the surface areas of the air/water interface for the beaker and tank, respectively, and $\frac{dm}{dt}$ is the time rate of change of the mass of water. The mass data from the beaker were fit with an exponential curve. The derivative $\frac{dm}{dt}$ was obtained from the analytical derivative of this curve fit; derivatives of other quantities required in this work were also obtained from analytical derivatives of the relevant curve fits. The surface temperature data, T_s , were fit with exponential curves as well. A linear least-squares regression was used to fit the γ and T_∞ data since these varied very little during the course of an experimental run. The temperature sensitivity of the fluid properties was accounted for when calculating h_m , Sh,

and Ra using the tabular data from Chapman [23], except for the diffusion coefficient, \mathcal{D} , which was obtained from the equation:

$$\mathscr{D}_{T} = \mathscr{D}_{298} \left(\frac{T}{298 \text{ K}} \right)^{3/2} \tag{21}$$

which is valid assuming the air/vapor mixture is an ideal gas, and that there is no variation in pressure [24].

The method for obtaining the densities used in Eqs. (8) and (10) follows the procedure presented in Sparrow et al. [18]. The density of water vapor in the air is obtained from:

$$\rho_{w\nu,\infty} = \gamma \rho_{sat}(T_{\infty}) \tag{22}$$

where $\rho_{sat}(T_{\infty})$ is obtained from the steam tables [25]. The air/vapor mixture density is obtained by:

$$\rho_{\infty} = \rho_{a,\infty} + \rho_{wv,\infty} \tag{23}$$

and $\rho_{a,\infty}$ is obtained from the ideal gas law with temperature set to T_∞ and pressure set to:

$$p_{a,\infty} = p_{tot} - p_{w\nu,\infty} \tag{24}$$

and p_{tot} set to one atmosphere. The densities at the surface are obtained using the same method as shown in Eqs. (22)–(24). That is, the mixture density at the surface is:

$$\rho_{s} = \rho_{a.s} + \rho_{wv.s} \tag{25}$$

where $\rho_{wv,s} = \rho_{sat}(T_s)$. The air density at the surface, ρ_{as} , is obtained from the ideal gas law in a manner similar to Eq. (24).

We note that, contrary to the work of Sparrow et al. [18], $\Delta \rho$ in Eq. (10) is defined to be positive when the air/vapor mixture at the surface is less dense than the surrounding air. Finally it should be noted that $\Delta \rho$ accounts for temperature effects and air/vapor density differences, and should not be confused with the $\Delta \rho_{wv}$ from Eq. (8) used in h_m which describes only the difference in water vapor densities.

A physical description of the evaporative and convective behavior of the system under study is presented in Fig. 2. Heat loss at the water surface occurs primarily through evaporation and natural convection with the air. This surface water cools, becomes more dense and descends through the bulk layer towards the bottom. The displaced warmer fluid rises through the bulk towards the surface. On the air-side of the interface, a buoyant plume structure forms due to two factors: (i) T_s is greater than T_∞ , and (ii) the relatively high concentration of water vapor at the surface makes the air/vapor mixture there less dense than the surrounding air. Hence, in a problem of this type, it is important to use $\Delta \rho$ in Ra from Eq. (9) instead of $\beta \Delta T$ as is often done when defining Ra.

3. Results

Time traces are presented in Fig. 3 for T_b , T_∞ , T_s , and γ from a sample experiment. As noted in the previous section, γ and T_∞ exhibit little variation during the course of an experiment, and this is

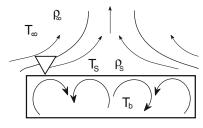


Fig. 2. Schematic of the transport processes at the air-side and water-side of the surface of a water tank.

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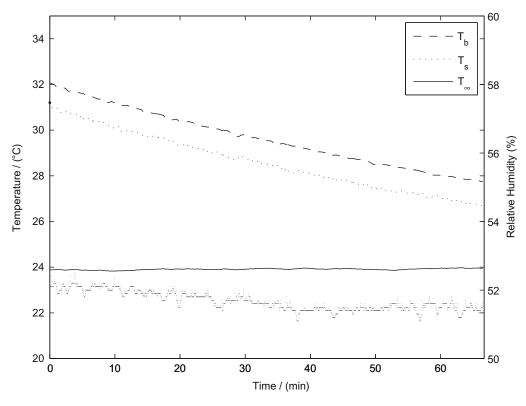


Fig. 3. Time trace of the bulk water, surface, and air temperatures and the relative humidity (lowest line in the plot) for a sample experimental run.

confirmed in Fig. 3. The mass data obtained for the beaker, also from a sample run, are shown in Fig. 4 along with the corresponding tank evaporation rate, calculated from the derivative of the exponential curve fit to the mass data.

A total of 63 experiments were conducted in this investigation, each with time traces similar to those shown in Figs. 3 and 4. The data were reduced to h_m using Eq. (7) and are plotted against $\Delta \rho/\bar{\rho}$ (Eq. (10)) in Fig. 5 where each line represents a single experimental run. In Fig. 5, h_m behaves as expected in that h_m increases with $\Delta \rho/\bar{\rho}$. There are a few experimental runs where h_m actually decreases with $\Delta \rho/\bar{\rho}$. While the reason for this behavior is unclear, the number of these anomalous runs is small and do not signifi-

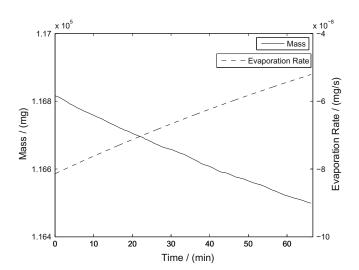


Fig. 4. Time series of the mass loss in the balance apparatus due to evaporation and the corresponding time derivative.

cantly affect the conclusions. It should be noted that this and subsequent figures show quantities that are obtained from curve fits to the raw data. Hence, individual data points are not presented.

The product of Sh and Ra is plotted against Ra in Fig. 6. In this figure, ShRa is plotted instead of Ra alone to reduce the effect of errors in the measurement of ΔT . Such errors propagate into $\Delta \rho$ since $\Delta \rho = \Delta \rho(\Delta T, \gamma)$. Therefore, ΔT is intrinsically present in the numerator of $\it Ra$ in Eq. (9) and in the denominator of $\it Sh$ via $\it \Delta \rho_{\it wv}$ in h_m from Eq. (7). Thus, by plotting *ShRa* versus *Ra*, the inclusion of errors in ΔT in both axes is avoided. The combined uncertainty of measurement and fitting errors results in an error in Ra of $\pm 2.04\%$ and an error in ShRa of $\pm 0.62\%$ (the uncertainty in Sh was $\pm 1.95\%$). The prefactors and exponents of the Sh-Ra power laws were obtained from a linear least-square fit to the logarithm of both Ra and ShRa. The resulting power law exponent, n, shown in Eq. (13) becomes (n + 1) when using the ShRa-Ra parameterization while the prefactor, B, remains the same. Henceforth, 1.0 has been subtracted from the exponent obtained in the ShRa-Ra power law relation to enable comparison to Sh—Ra power law relations in the literature. Finally, it is noted that the range in Ra in Fig. 6 was obtained in two ways, first by using tanks of different width, and secondly via the range in ΔT that existed during the course of each experimental run.

4. Discussion

The main results of this work are summarized in Fig. 6. This plot of *ShRa* versus *Ra* yields the following power law:

$$Sh = 0.230Sc^{1/3}Ra^{0.321} (26)$$

This result was obtained for a range of Ra spanning three decades. The uncertainty in the exponent is ± 0.0096 and the uncertainty in the prefactor is ± 0.0383 . It is noted that n in Eq. (26) differs from 1/3 by less than 4%. This result is of particular interest for two rea-

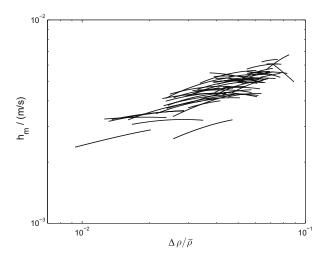


Fig. 5. Plot of h_m versus $\Delta \rho / \bar{\rho}$ for all runs.

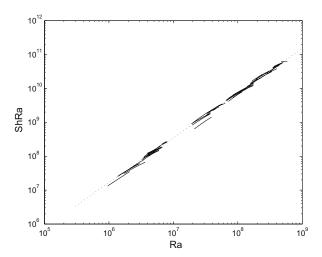


Fig. 6. The air-side ShRa-Ra power law represented by the dotted line, which gives B=0.230 and n=0.321+1. Data were acquired using tanks having widths of 15.2 cm, 30.5 cm, 45.7 cm, and 60.9 cm.

sons. First, a value close to 1/3 is often found for the exponent m in turbulent natural convection heat transfer studies using a power law relation between the Nusselt and Rayleigh numbers:

$$Nu = CRa^m (27)$$

where the Nusselt number is defined as:

$$Nu = hL/k \tag{28}$$

Here, h is the heat transfer coefficient, L is the characteristic length usually defined as the vertical distance between the heated/cooled plates in the traditional Rayleigh–Bénard setup, and k is the thermal conductivity of the fluid. For example, Globe and Dropkin [26] found m=1/3, Chu and Goldstein [27] show m=0.278, and Niemela et al. [28] give m=0.309 for a range of Ra spanning 11 orders of magnitude. Many other studies exist, and a good review is provided in Chavanne et al. [29] who show that with few exceptions $m\cong 0.3$. The similarity between m and the value of n attained here exists in spite of the fact that the present investigation concerns mass transfer in parallel with heat transfer, as opposed to pure heat transfer, and the boundary conditions are very different. For example, in Rayleigh–Bénard convection experiments, typically there is a solid plate bounding the top and the bottom of a fluid layer, making the problem one where the hydrodynamic boundary condition is of

the no-slip kind. In the present experiment, the air resides above an air/water interface which is a free surface and therefore lacks the no-slip boundary condition. Moreover, there is (effectively) no upper boundary for the air, and the length scale used in this study is the width of the tank, a horizontal scale, while in the Rayleigh-Bénard case, the length scale is the vertical distance between the two solid plates. The fact that we attain such a similar value for the power law exponents m and n in spite of these differences suggests a certain robustness in the power law relationship between these two dimensionless heat and mass transfer coefficients (viz. the Nusselt and Sherwood numbers) and the Rayleigh number. Furthermore, this suggests that the characteristics of turbulence that control the transport are more important than the specific details of the boundary conditions or even the quantity being transported (mass versus heat).

The second reason the similarity of n to 1/3 is significant concerns the characteristic length in the definition of Ra and Sh. Below, the Sh-Ra power law correlation from Eq. (13) is shown in expanded form using n = 1/3:

$$\frac{h_m W}{\mathscr{D}} = BSc^{1/3} \left(\frac{g(\rho_{\infty} - \rho_{s})W^3}{\bar{\rho}v\alpha} \right)^{\frac{1}{3}}$$
 (29)

which allows for the cancellation of the characteristic length, and reduces to:

$$h_m \sim \left(\frac{\rho_\infty - \rho_s}{\bar{\rho}}\right)^{1/3} \sim \left(\frac{\Delta \rho}{\bar{\rho}}\right)^{1/3}$$
 (30)

showing that the characteristic length has no effect on h_m when n=1/3. The fact that the value of n obtained here is very close to 1/3 indicates a corresponding lack of sensitivity of h_m to length scale for evaporation driven by natural convection, at least under the conditions explored here.

Table 1 presents the exponents and prefactors for the Sh—Ra power law obtained from the present study and those studies cited in Section 1. The Schmidt number for the working fluid used in each study is also presented. In lines 1-4 of Table 1, the length scale used in the definition of Ra and Sh is the typical characteristic length, namely the width or diameter of the water tank or pan. In lines 5–8, the length scale L^* (Eq. (17)) is used in computing Ra and Sh. This is because Goldstein et al. [21] and Lloyd and Moran [22] employed planforms of several different geometries necessitating the use of this length scale to collapse their data. To facilitate comparison with these two studies, the present data is also reformulated using L^* , and the resulting prefactor and exponent are presented in line 5. It is noted that the magnitude of the Rayleigh numbers attained when using L^* as a length scale are significantly reduced. Finally we note that two entries are provided for the work of Lloyd and Moran [22], line 7 for their turbulent results and line 8 for the laminar results.

The exponent obtained in the present work is significantly larger than that obtained by the other studies presented in the first four lines of Table 1, 45% larger than the average of these three other studies. The effect of this difference in n can be seen in Fig. 7 where the present data has been plotted along with that obtained from the studies cited in lines 2 and 3, graphically showing the difference in slope. In lines 5–8 of Table 1 our exponent is very close to the turbulent value of Lloyd and Moran [22] (which differs from the present value by less than 2%), and different from the remaining studies, both of which give exponents close to 1/4.

A possible explanation for the difference/similarity between n from the present work and the cited literature concerns the range in Ra pursued in these studies, and in the effect of airflow restriction on evaporation. Referring to lines 2–4 of Table 1, n increases monotonically with the maximum Ra explored in the study. The

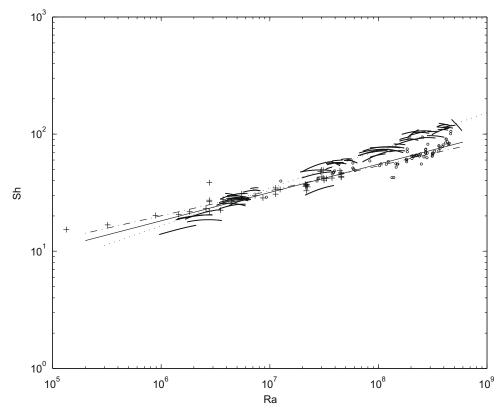


Fig. 7. Comparison of the present results (dotted power law line and solid data lines) with those of Sharpley and Boelter (dash-dot line and + data symbols) and Boelter et al. (solid line and circles) on Sh versus Ra coordinates.

present work has a maximum Ra larger than all three of those studies, and has the largest n. Of course, the maximum Ra of the present study is only slightly larger than that of Boelter et al. [20] $(5.7 \times 10^8 \text{ compared to } 4.6 \times 10^8)$, yet the difference in n is large. Hence, additional explanation is needed. As noted in Section 1, the studies cited in lines 2–4 were all conducted in facilities where the flow of air to the water tank or pan was significantly restricted, at least compared to the present work where the water tank was placed in a laboratory without a housing or other structure to impede air flow. It is possible that this is the other factor that accounts for the larger n found here compared to the aforementioned authors. That is, our value of n is larger because the flow of air above the water is less restricted, enabling Sh to increase more readily with increasing Ra.

A similar argument can be made for the studies cited in lines 6–8 of Table 1. Here, the work of Goldstein et al. [21] results in n=.250 for values of Ra_{L^*} much smaller than that attained in the present study, supporting the idea that n is small when the Rayleigh numbers are relatively small. The work of Lloyd and Moran [22] yield n very close to that attained herein when their values of Ra_{L^*} are significantly larger than that of the present study. They also attain a value of n that is smaller than ours when their range in Ra_{L^*} is comparable to ours. Again, a possible explanation is that, in Lloyd and Moran [22], the flow restrictions inherent in their apparatus result in a small exponent (n=0.255) even when the Ra_{L^*} range is essentially the same as the present work.

The above discussion tends to suggest that smaller values of n will be attained at lower Ra, at least below some limiting value of Ra. This confirms prior work which has shown that n=1/4 for low Ra, but increases at larger Ra [20]. There is abundant research in the heat transfer literature to suggest that above a relatively low value of Ra, $m \cong 0.3$ with relatively small changes in m with increasing Ra, similar to what is seen here with evaporation [26–29].

Finally, we raise the somewhat subtle question of whether water-side natural convection can affect evaporation. To first order, any effect of water-side motion should be accounted for in the air-side definitions of Ra and Sh. For example, vigorous natural convection on the water side could easily change the surface temperature, and hence evaporation rate, however such a change in T_s is accounted for in the variables $\rho_{wv,s}$ and ρ_s used in Eqs. (8) and (10), which are in turn used in the present definitions of Sh and Ra. On the other hand, one might argue that for a given average T_s , two different tanks having different water-side Rayleigh numbers due to different depths will have different water-side turbulence intensities giving, for example, a different value for the root mean square of T_s . The question then is: will such an effect have an impact on Sh? The data acquired here can begin to address this question, since tank depth D was varied.

Fig. 8 presents Sh plotted against Ra_D , which is the water-side Rayleigh number defined as:

$$Ra_D = \frac{g\beta\Delta TD^3}{v\alpha} \tag{31}$$

where β is the volume expansivity, D is the tank depth, $\Delta T = T_b - T_s$, and all fluid properties are for liquid water. The curve fits are coded according to tank width revealing, as expected, a strong vertical separation of the data according to width. The plot also shows, however, a small increase in Sh with Ra_D for each tank width, tempting one to surmise that water-side natural convection plays a role in evaporative transport. These data are now replotted in Fig. 9(a) on h_m versus Ra_D coordinates, also showing a slight increase with depth. In Fig. 9(b), representative runs are plotted on h_m versus T_s coordinates. Careful observation of Fig. 9(a) and (b) shows that h_m increases both with T_s and with depth. That is, Fig. 9(b) shows that for each progressively deeper tank, T_s becomes higher. This may in fact be due to an experimental artifact. Namely, due to the procedure of waiting 1 h prior to initiating data acquisition, the shallower

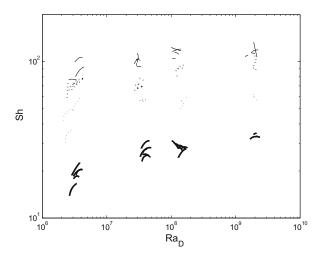
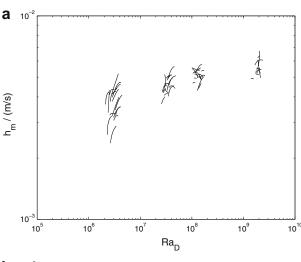


Fig. 8. Plot of Sh versus water-side Rayleigh number Ra_D . Line type is according to tank *width*: thick solid line – 15.2 cm; thin dotted line – 30.5 cm, thick dashed line – 45.7 cm; and thin solid line – 60.9 cm.



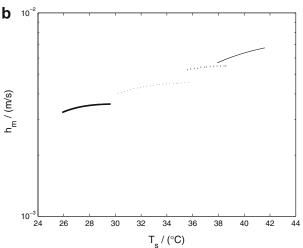


Fig. 9. (a) Plot of h_m versus the water-side Rayleigh number, Ra_D . (b) Plot of h_m versus T_s . In (a), the data are clumped according to tank *depth*, from left to right: D = 5.1 cm, 10.2 cm, 15.2 cm, and 35.5 cm. In (b) a single representative time trace is presented for each tank *depth* to reveal the apparent trend. Depth: thick solid line -5.1 cm; thin dotted line -10.2 cm; thick dashed line -15.2 cm; and thin solid line -35.5 cm.

tank runs started at a significantly lower initial T_s than the deeper tanks. Hence Fig. 9(b) may be showing larger h_m in deeper tanks simply because these tanks had larger values for T_s . Since the air temperatures were relatively constant, this larger T_s corresponds to a larger air-side ΔT and a correspondingly larger air-side Rayleigh number. Thus what seems like an effect of depth may simply be that deeper tanks had larger air-side Rayleigh numbers, resulting in larger Sh.

To determine whether water depth can affect the evaporation rate, experiments conducted at constant tank width over a range of tank depths would be needed with the critical requirement that the range of air-side ΔT overlap for the different tank depths. Since T_{∞} is essentially a constant, this requirement is essentially that the range of T_s be the same for each tank depth. As shown in Fig. 9(b), there is essentially no overlap in T_s for all four tank depths evaluated in this work, preventing us from making a conclusive statement one way or the other regarding the effect of depth. Overall, this effect is not expected to be large, but may have some significance in environmental applications where very large depth variations exist.

5. Conclusion

Data were collected from a set of water tanks undergoing natural convection-driven evaporation. These data were reduced to a dimensionless mass transfer coefficient for evaporation, Sh, and related to the air-side Rayleigh number Ra via a power law. The resulting *Sh*–*Ra* power law exponent was $n = 0.321 \pm 0.0096$ and the prefactor was $\textit{B} = 0.230 \pm 0.0383$. The value of the exponent is close to 1/3, a value similar to power law exponents obtained in many Nu-Ra studies of natural convection heat transfer. The similarity between these power law equations suggests that the characteristics of turbulence dictate transport phenomena in a way that transcends the relevant length scale, or even the quantity being transported. At the same time, comparison with prior laboratory studies of evaporation suggests restriction of air flow in the vicinity of the evaporating surface can significantly affect n. Finally, comparison with prior work confirms that a value of n close to 1/3is not achieved until Ra is sufficiently large.

Acknowledgments

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