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### Technical note

# Parametric investigation of two aerosol scavenging models in the inertial regime

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#### ABSTRACT

Models of drop scavenging of aerosols via inertial impaction proposed by Slinn and by Calvert are compared with published experimental measurements to determine which model is a better predictor of the data. Additionally, a parametric study was performed on the residual of the model predictions from the measurements to identify dimensionless groups not included in these models, which might increase model performance. The study found that the Calvert model predicts scavenging in the inertial regime with less error than the Slinn model. The study also found that two dimensionless groups, the relative Stokes number,  $Stk_r$ , and the drop Reynolds number,  $Re_D$ , are both well correlated with the residual of these models. They are included in modified versions of both of these models to provide better performance. That these two dimensionless groups improve model performance suggests that an inertial mechanism and an advective mechanism not accounted for in the existing models play some role in aerosol scavenging in the inertial regime.

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#### 1. Introduction

Understanding how a drop, such as a rain drop or a spray drop, removes aerosols has a wide range of applications, from atmospheric particulate removal (Greenfield, 1957) and climate modeling (Adams & Seinfeld, 2002; Roeckner et al., 2003; Wang, Zhang, & Moran, 2010; Webster & Thomson, 2014) to dust control in mining and industrial processes (Calvert & Goldshmid, 1972; Kissell, 2003; Schnelle & Brown, 2002; Walton & Woolcock, 1960). Aerosol scavenging by drops is quantified by the scavenging coefficient, *E*, which is the ratio of the number of particles collected by the drop,  $n_c$ , to the total number of particles within the air column through which the drop passed,  $n_t$ :

$$E = \frac{n_c}{n_t} \tag{1}$$

which ranges from zero to unity. The streamlines around a drop do not intersect that drop, and so values for *E* are primarily caused by particles deviating from the streamline that they are on (an exception to this statement being the interception mode of scavenging, described below). For example, a relatively large particle will have significant inertia and will deviate from its streamline as that streamline curves around the drop, impacting the drop, and causing the particle to be scavenged from the flow. This is called the inertial mode of deposition (Beard & Grover, 1974; Hinds, 1982; Langmuir, 1948; Slinn, 1984),

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and is the scavenging mode which this paper is focused upon. In contrast, for particles that are very small and have essentially zero inertia, Brownian motion can cause the particles to deviate from their streamlines, moving toward the drop. This is referred to as diffusional deposition (Hinds, 1982; Levich, 1962; Slinn, 1984). Finally, particles that nominally remain on their streamline, but are on a streamline that comes within half the particle diameter from the drop surface will strike the drop, a process called interception (Friedlander, 1977; Hinds, 1982; Slinn, 1984). In addition to these three primary modes of deposition, there also exist particle scavenging due to processes such as phoretic effects and charging (Park, Jung, Jung, Lee, & Wet, 2005; Slinn, 1984; Wang et al., 2010). The reader is referred to Wang, Leong, Stukel, and Hopke (1983) for a more detailed discussion of these various mechanisms.

One goal of the present work is to determine whether the inertial model due to Slinn (1984) and Slinn et al. (1977) or the inertial model due to Calvert and Englund (1984) and Calvert (1970) (described in detail below) is more accurate by comparing their predictions to experimentally measured scavenging coefficients,  $E_m$ . The second goal of this work is to identify additional dimensionless groups that can be used to improve these models so that they better predict  $E_m$ . In addition to providing improved versions of the two models, it is hoped that the identified dimensionless groups will help to identify other physical mechanisms which play a role in the inertially dominant scavenging regime.

#### 2. Model descriptions

The present study is focused on models for the inertial mechanism of scavenging. There are only two models used for inertial impaction in the recent literature surveyed (Ardon-Dryer, Huang, & Cziczo, 2015; Chate, Murugavel, Tiwari, & Beig, 2011; Davenport & Peters, 1978; Park et al., 2005; Seinfeld & Pandis, 2006; Wang et al., 2010): the model due to Slinn (1984) and Slinn et al. (1977) and the model due to Calvert and Englund (1984) and Calvert (1970). Both of these models are empirical fits: the Slinn model for scavenging via inertial impaction is a fit to numerical simulations due to Beard and Grover (1974), and the Calvert model for scavenging via inertial impaction is a fit to the experimental results of Walton and Woolcock (1960). Both models are predictions of the contribution of inertial impaction to the scavenging coefficient *E* and will be referred to hereinafter as  $E_S$  and  $E_C$  for Slinn and Calvert, respectively. Also, the thing being scavenged in the following models is referred to as a particle, and the subscript "*p*" is used to refer to properties of the thing being scavenged; however the models apply to any aerosol.

Slinn's inertial model is:

$$E_{\rm S} = \beta \left(\frac{\rho_p}{1000}\right)^{1/2} \left(\frac{Stk - Stk_*}{Stk - Stk_* + 2/3}\right)^{3/2} \tag{2}$$

where  $\rho_p$  is the particle density and *Stk* is the Stokes number:

$$Stk = \frac{(\rho_p - \rho_a)d^2UC}{9D\mu_a}$$
(3)

where  $\rho_a$  is the air density, *d* is the particle diameter, *U* is the drop velocity, *D* is the drop diameter,  $\mu_a$  is the air dynamic viscosity, and *C* is the Cunningham correction factor:

$$C = 1 + \frac{2\lambda}{d} \left[ 1.257 + 0.4 \exp\left(\frac{-0.55d}{\lambda}\right) \right]$$
(4)

 $\lambda$  is the mean free path in air and  $Stk_*$  is the critical Stokes number:

$$Stk_{*} = 1.2 + \frac{1}{12} \left( \frac{\ln(1 + Re_{D})}{1 + \ln(1 + Re_{D})} \right)$$
(5)

where  $Re_D$  is the drop Reynolds number:

$$Re_D = \frac{\rho_a DU}{\mu_a} \tag{6}$$

The critical Stokes number  $Stk_*$  is the value of Stk below which the particle does not possess sufficient inertia to overcome viscosity and will not come into contact with the drop surface (Beard & Grover, 1974; Friedlander, 1977; Fonda & Herne, 1957; Langmuir, 1948);  $\beta$  is a step function which limits  $E_5$  to only the inertial regime:  $\beta = 1$  if  $Stk > Stk_*$  and  $\beta = 0$  otherwise. Using a potential flow solution for flow over a drop gives  $Stk_* = \frac{1}{12}$  (Beard & Grover, 1974; Friedlander, 1977; Fonda & Herne, 1957), and  $Stk_*$  is slightly greater than unity when using a Stokes flow solution (Beard & Grover, 1974; Fonda & Herne, 1957; Langmuir, 1948). Equation (5) is obtained via an interpolation scheme between these two solutions (Slinn, 1984; Slinn et al., 1977).

As Eq. (2) is an empirical fit to Beard's numerical simulations, it follows that it is subject to the same assumptions as Beard's simulation (Beard & Grover, 1974). Briefly, this simulation traced the path of particles introduced far upstream of a spherical drop, and considered no forces other than those due to the flow and to inertia. These assumptions preclude particle impacts on the drop surface due to the hydrodynamic barrier effect. Accordingly it was assumed that once any particle came within several microns of the drop, other forces, such as an electrostatic force, would become dominant and

allow for the particle to penetrate this barrier. Of note, this simulation is identical to the simulation of Langmuir (1948), however due to advances in computing technology it was solved with greater precision. Also, this simulation implicitly assumed that there was no particle bounce off, so that all particles which contact the drop are removed from the system.

The second inertial model is that due to Calvert:

$$E_C = \left(\frac{Stk}{Stk + 0.35}\right)^2 \tag{7}$$

Calvert's model is an empirical fit to the experimental data of Walton and Woolcock (1960) which was obtained from pendant drops and therefore may not be a perfect representation of falling drops, making the application of Calvert's model to falling drops problematic. For example, pendant drops do not experience the same drop oscillations as falling drops, and the wake structure behind a pendant drop will differ from that of a falling drop. Furthermore, the data of Walton and Woolcock (1960) only spanned  $0.05 \le Stk \le 1.32$ ; therefore applying the Calvert model outside of this range may cause problems as well. We note in passing that Calvert's model does not include the critical Stokes number, and the author makes no statement that the model should not be used below this value (Calvert, 1970; Calvert & Englund, 1984). This uncertainty of application is of no bearing here, however, since this paper is only concerned with the inertial range.

#### 3. Experimental comparisons

Numerous experimental studies of particle scavenging by drops exist, however many of these studies do not provide data for  $Stk > Stk_*$  (Ardon-Dryer et al., 2015; Beard, 1974; Byrne & Jennings, 1993; Hampl & Kerker, 1972; Hampl, Kerker, Cooke, & Matijevic, 1971; Ladino et al., 2011; Lai, Dayan, & Kerker, 1978; Vohl, Mitra, Kiehl, & Huber, 2001; Wang & Pruppacher, 1977a) and therefore will not be included in the present analysis of inertial regime scavenging. The inertial regime experimental studies considered here are the work of Quérel, Monier, Flossmann, Lemaitre, and Porcheron (2014), Chate and Kamra (1997), Pranesha and Kamra (1996), Leong, Beard, and Ochs (1982), Starr and Mason (1966), and Gunn and Hitschfeld (1950), who performed experiments in the inertial regime using fall towers. Walton and Woolcock (1960) performed experiments in the inertial regime in a vertical wind tunnel. Other inertial regime studies include Ranz and Wong (1956), Hähner, Frank, Dau, Günter, and Ebert (1994), and Waldenmaier (1999) who performed experiments in the inertial regime using horizontal wind tunnels. These studies, however, presented scavenging results only in terms of *Stk* and *D*, and due to the flow geometry it could not be assumed that the experiments took place at terminal velocity. This made it impossible to compute groups such as *Re<sub>D</sub>*, which were needed to compare their results to the model predictions, and so they are not considered further hereinafter.

To compare the measured scavenging coefficients,  $E_m$ , obtained from the studies cited above, to the predicted values,  $E_C$  and  $E_S$ , the values of *Stk* and  $Re_D$  were computed from the data provided for each reported data point in the experimental studies cited above. These values were then inserted into Eqs. (2) and (7) to provide  $E_S$  and  $E_C$ , respectively. Any data that fell outside of the inertial regime were ignored. All reported data were assumed to have been obtained at standard temperature and pressure. For the fall tower studies, the relative velocity between the drop and particles was assumed to be terminal, with the terminal velocity computed using the equation developed by Beard (1976).



**Fig. 1.** Predicted versus measured scavenging coefficients comparing (a) Slinn's model and (b) Calvert's model. The data sets are:  $\circ$ , Walton and Woolcock (1960);  $\Box$ , Quérel et al. (2014);  $\diamondsuit$ , Chate and Kamra (1997);  $\triangledown$ , Pranesha and Kamra (1996);  $\triangle$ , Leong et al. (1982) and Starr and Mason (1966); and  $\triangleleft$ , Gunn and Hitschfeld (1950). The Calvert model has better agreement with the surveyed scavenging measurements by virtue of the larger value of *r* and the smaller value of *S* for that model. Only experimental data falling within the inertial regime were used.

The model predictions  $E_S$  and  $E_C$  are plotted against  $E_m$  in Fig. 1 along with a unity slope line. Two figures of merit are used to evaluate the similarity of the model to the data. The first is the correlation coefficient:

$$r = \frac{\sum (x_i - \overline{x})(y_i - \overline{y})}{\sqrt{\sum (x_i - \overline{x})^2} \sqrt{\sum (y_i - \overline{y})^2}}$$
(8)

The second figure of merit is the standard error of fit of the data to a unity slope line:

$$S = \sqrt{\frac{\sum (y_i - F(x_i))^2}{n-2}}$$
(9)

In the above equations  $x_i$  are the experimental measurements,  $y_i$  are the model predictions, and F is the unity slope line. Values for r and S are presented in Fig. 1. To provide a more meaningful comparison of the predictive capability of the two models presented in Fig. 1,  $E_S$  and  $E_C$  were multiplied by a constant that minimized the vertical deviation of the data from the unity slope line. This constant was obtained from the vertical intercept of a least-squares regression on the data in log space. This procedure ensured that the magnitude of r and S was determined by failures of the functional form of  $E_{\rm S}$  and  $E_{\rm O}$ . and not by the lack of a simple multiplicative constant. This constant is included in the label of the ordinate in Fig. 1.

As Fig. 1 shows, the Calvert model does a better job of predicting the data as measured by both r and S. It is noted that the Calvert model is empirically based upon a subset of the data used here, namely the Walton and Woolcock data set. Hence, it is possible that the better performance of the Calvert model is due to the presence of data used in developing that model. To determine if this was the case, the Walton and Woolcock data was removed and new values of r and S were calculated for both models, giving r=0.624 and S=0.588 for  $E_S$  and r=0.747 and S=0.207 for  $E_C$ , showing that the Calvert model continued to perform better, even without the presence of the Walton and Woolcock data. Hence, the Calvert model is the preferred model for predicting scavenging. This result satisfies the first goal of this work, which was to determine which of the two models investigated is preferred for predicting scavenging in the inertial regime.

#### 4. Analysis

In order to improve the models of Slinn and Calvert, the log space residual error, e was computed for each model, where e is defined as:

$$e = \log_{10}(E_m) - \log_{10}(E) \tag{10}$$

Note that the prefactor from Fig. 1 is not used in this equation nor in subsequent equations for e. This residual was related to each of six dimensionless groups  $\phi$ , five of which were identified via a Buckingham Pi analysis, as described below. Specifically, e was related to the dimensionless groups  $\phi$  via a the power law:

$$e = f_1(\phi) = A\phi^0 + B \tag{11}$$

where (A, b, B) were found via nonlinear least squares regression. The goodness of the fit was quantified via r and S. This was done for each of the six  $\phi$  considered and the  $\phi$  with the largest r and smallest S were deemed to contribute the most to the residual error and were then used to create an improved model E':

$$E' = E \times 10^{f_1(\phi)}$$
(12)

The above process was then repeated, generating a new residual  $f_2(\phi)$  for the revised model and correcting it to form a twice-improved model, E. This process was continued until the most correlated  $\phi$  yielded a correlation coefficient that was less than 0.60. Such a cutoff was needed to give a definite end to the above procedure. The value of 0.6 was somewhat arbitrary; cutoff values smaller than 0.60 resulted in models that were excessively complex and did not visually improve the collapse of the data to the unity slope line in plots such as that presented in Fig. 1.

As noted above, five of the  $\phi$  were obtained using a Buckingham Pi analysis. Assuming that E is a function of D, d,  $\rho_p$ ,  $\rho_a$ ,  $\mu_a$ , U, gravitational acceleration, g, and the particle diffusivity,  $\mathcal{D}$ , then E will be a function of the five dimensionless groups:

Correlations of various dimensionless groups for the residual of $E_s$ .			
φ	r	S	$f_1(\phi)$
Stk <sub>r</sub>	0.854	0.312	$-3.075tk_r^{0.173}+2.72$
Stk	0.784	0.374	$0.0694Stk^{-2.38} - 0.231$
Ре	0.740	0.405	$-1.98 \times 10^{-12} Pe^{1.18} + 0.714$
$Re_d$	0.701	0.429	$-0.747 Re_d^{0.64} + 1.4$
Re <sub>D</sub>	0.647	0.458	$-1.19 \times 10^{-6} Re_D^{1.72} + 0.613$
Fr	0.114	0.598	$3.19 \times 10^{13} Fr^{-6.64} + 0.25$

φ	r	S	$f_1(\phi)$
Re <sub>D</sub>	0.633	0.166	$-4.15 \times 10^{-16} Re_{p}^{4.35} - 0.101$
Pe	0.463	0.190	$-3.7 \times 10^{-16} Pe^{1.49} - 0.107$
Fr	0.326	0.203	$3.19 \times 10^{-3} Fr^{0.517} - 0.35$
Red	0.187	0.211	$-0.065 Re_d^{0.683} - 0.095$
Stk	0.084	0.214	$5.14 \times 10^{-3} Stk^{1.69} - 0.207$
Stk <sub>r</sub>	0.063	0.214	$-9.94 \times 10^{-5} Stk_r^{-0.885} - 0.196$

**Table 2** Correlations of various dimensionless groups for the residual of  $E_{c}$ .

*Re<sub>d</sub>*, *Re<sub>D</sub>*, *Stk*, the Péclet number, *Pe*, and the Froude number, *Fr*. Additionally a relative Stokes number, *Stk<sub>r</sub>* was developed for this analysis:

$$Stk_r = \log_{10}\left(\frac{Stk}{Stk_*}\right) \tag{13}$$

which cannot be obtained from the Buckingham Pi analysis. This dimensionless group is a measure of the particle's inertia relative to the critical value, and is a measure of how far into the inertial regime an experimental condition lies. It was thought to provide a measure of inertia potentially better than *Stk* alone, a supposition borne out by the following results.

The resulting functions for the first iteration of the above process,  $f_1$ , are presented in Tables 1 and 2 for the Slinn and Calvert models, respectively. Note that the subscripts *S* and *C* will be used for Slinn and Calvert, respectively. These tables show that the two model residuals are best described by different dimensionless groups:  $e_S$  is best described by  $Stk_r$  and  $e_C$  is best described by  $Re_D$ .

Tables 3 and 4 present the residual, e', between  $E_m$  and E':

$$e' = \log_{10}(E_m) - \log_{10}(E') \tag{14}$$

as well as the power law relationships,  $f_2(\phi)$ , relating  $\phi$  and e'. As Table 4 shows, the modified Calvert model is not well correlated with any of the investigated dimensionless groups, its correlation coefficient being less than 0.60 for all  $\phi$  considered. Thus, the modified Calvert model is  $E'_{c}$ :

$$E'_{c} = E_{c} \times 10^{-4.15 \times 10^{-16} Re_{D}^{4.35}} \times 10^{-0.101}$$
<sup>(15)</sup>

Table 3 shows a significant correlation between  $e'_{S}$  and  $Re_{D}$ , and so the above process was repeated yet again for that model, resulting in the correlations shown in Table 5. As all of the correlation coefficients are less than 0.60 in Table 5, we consider the doubly modified model as the revised Slinn model:

$$E_{s}^{'} = E_{s}^{'} \times 10^{f_{2}(Re_{D})}$$
(16)

or, via substitution:

$$E_{\rm S}^{"} = E_{\rm S} \times 10^{-3.075tk_{\rm F}^{0.173}} \times 10^{-2.61 \times 10^{-14} Re_{\rm D}^{3.9}} \times 10^{2.905}$$
(17)

Equations (17) and (15) are the improved versions of the Slinn and Calvert models, respectively, which achieve the second goal of this work, to improve upon the accuracy of their original versions. These equations are reproduced below:

$$E_{S}^{*} = E_{S}^{*} = E_{S} \times 10^{-3.075 k_{r}^{0.173}} \times 10^{-2.61 \times 10^{-14} Re_{D}^{3.9}} \times 10^{2.905}$$
(18)

$$E_{\rm C}^* = E_{\rm C} = E_{\rm C} \times 10^{-4.13 \times 10} \quad \text{M}_{\rm D} \quad \times 10^{-0.101} \tag{19}$$

Plots of the original and improved Slinn and Calvert models are presented in Fig. 2, showing significantly improved collapse of the data to the unity slope line for the improved models.

#### Table 3

Correlations of various dimensionless groups for the residual of  $E'_{S}$ .

φ	r	S	$f_2(\phi)$
Re <sub>D</sub>	0.803	0.186	$\begin{split} &-2.61\times 10^{-14}Re_{0}^{3.9}+0.185\\ &-6.68\times 10^{-16}Pe^{1.49}+0.162\\ &-6.06\times 10^{-15}Stk_{r}^{-4.11}+0.009\\ &7.24\times 10^{-6}Stk^{-8.15}-0.036\\ &9.89\times 10^{-8}Fr^{1.55}-0.020\\ &-0.098Re_{d}^{0.59}+0.144 \end{split}$
Pe	0.568	0.257	
Stk <sub>r</sub>	0.272	0.301	
Stk	0.261	0.302	
Fr	0.192	0.307	
Re <sub>d</sub>	0.158	0.308	

#### Table 4

Correlations of various dimensionless groups for the residual of  $E'_{C}$ .

$\phi$	r	S	$f_2(\phi)$
Fr Re <sub>D</sub> Stk <sub>r</sub> Pe Stk	0.432 0.263 0.228 0.167 0.141	0.15 0.160 0.162 0.164 0.165	$0.584Fr^{0.0913} - 1.140$ $0.395Re_D^{0.052} - 0.549$ $-0.0635tk_r^{-0.217} + 0.091$ $0.060Pe^{0.069} - 0.263$ $4.69 \times 10^{-24}Stt^{-38.3}$
Re <sub>d</sub>	0.130	0.165	$-0.169Re_d^{-0.202} + 0.153$

#### Table 5

Correlations of various dimensionless groups for the residual of  $E_{s}^{'}$ .

φ	r	S	$f_3(\phi)$
Stk <sub>r</sub>	0.567	0.153	$-8.04 \times 10^{-15} St k_r^{-4.11} + 0.011$
<i>Re</i> <sub>d</sub>	0.390	0.171	$-0.222Re_d^{-0.504}+0.179$
Fr	0.348	0.174	$-3.78Fr^{-0.384}+0.232$
Re <sub>D</sub>	0.326	0.176	$-0.731 Re_{D}^{-0.451} + 0.057$
Ре	0.322	0.176	$-276Pe^{-0.399}+0.070$
Stk	0.200	0.182	$0.032 Stk^{0.978} - 0.034$

#### 5. Discussion

We now address the question of whether the dimensionless groups used in revising the equations of Slinn and Calvert may provide insight on additional mechanisms governing scavenging in the inertial regime. The dimensionless groups  $Stk_r$  and  $Re_D$  were used to revise the models.  $Stk_r$  is discussed first.

Figure 3 presents the residual,  $e_s$ , versus  $Stk_r$ , showing that  $e_s$  is high when  $Stk_r$  is near zero, but decreases as  $Stk_r$  increases. This implies that  $E_s$  under-predicts scavenging near the transition to the inertial regime, but improves as  $Stk_r$  increases. This indicates that there exists some mechanism that is not well accounted for in  $E_s$  which plays a role in scavenging during the transition to inertially dominated scavenging. In comparison,  $Stk_r$  is the least well correlated dimensionless group for  $e_c$ .

Recall that  $E_s$  is solely based upon inertial impaction simulations by Slinn et al. (1977) and Beard and Grover (1974), while  $E_C$  is solely based upon experimental measurements of particle collection by pendant drops performed by Calvert (1970) and Walton and Woolcock (1960). This provides information regarding what additional mechanisms could be contributing to scavenging in the transition to the inertial regime. The fact that  $e_C$  is uncorrelated to  $Stk_r$  for even freely falling drops indicates that this mechanism is likely present for both pendant drops and for drops in free fall. This rules out any mechanisms which rely on the back half of the drop, as that is where a pendant drop would be supported. It also likely rules out any mechanism related to drop oscillations as a pendant drop will be relatively pinned due to its support.

A possible mechanism fitting these requirements would be the inertial compression of the particle phase on the front hemisphere of the drop. This mechanism is an inertial enhancement of diffusional deposition caused by inertially increasing the particle concentration near the drop surface. It was proposed by de la Mora and Rosner (1982), and would correspond to larger scavenging near  $Stk_r = 0$ . This is because as particles approach the drop they will deviate from their streamlines due to inertia; as  $Stk_r$  increases this deviation becomes larger and the resulting scavenging increases. However, at low  $Stk_r$  very few particles will be deflected enough to allow for inertial impaction on the drop. Instead the majority of affected particles will become more closely packed near the drop surface, resulting in an increase in the local concentration of particles near the drop surface relative to the freestream concentration. Because of the particle phase compression there is an increased concentration gradient near the drop, which will result in a greater mass transfer of the particle phase to the drop surface via diffusional deposition.

The contribution of this mechanism to scavenging will diminish, however, as the inertia of the particles is increased. This is due to two mechanisms: first more particles will be scavenged due to inertial impaction as *Stk* increases; second, as *Stk* increases the required time for a particle to travel around the drop will become significantly shorter than its relaxation time, meaning that there will be less time for the inertial compression of the particle phase to enhance mass transfer to the drop surface. As this mechanism would be present in any of the experimental measurements considered here, and it agrees with the trend in Fig. 3, it is a possible explanation for some of the residual observed with the Slinn model.

The other dimensionless group that was well correlated with the model residuals was  $Re_D$ , as shown in Tables 2 and 3. Figure 4 presents plots of the residual versus  $Re_D$  for both models, showing similar behavior for both models. Hence, the mechanism which  $Re_D$  describes is most likely not accounted for by either model. A possible mechanism that could account for this trend is wake capture of particles. Wake capture occurs when a particle traverses the front end of the drop without



Fig. 2. Plots of model prediction versus experimental data: (a) and (b) are the unmodified Slinn and Calvert models, respectively; (c) and (d) are the final, modified Slinn and Calvert models, respectively.

being scavenged but is then pulled into the recirculating region in the drop wake and is ultimately deposited on the back side of the drop after one or more passes in this recirculating region. Wake capture is often used to explain scatter in experimental data (Beard, 1974; Goldshmid & Calvert, 1963; Quérel et al., 2014; Wang & Pruppacher, 1977b). However, to the authors' knowledge there has been no rigorous study of the wake capture of particles by a falling drop. Sakamoto and Haniu (1990) showed that the wake dynamics for a sphere are primarily a function of  $Re_D$ , with vortex shedding beginning to occur at  $Re_D \sim 300$ . This corresponds with the trends in Fig. 4, as there is a large drop off in the residual for  $Re_D > 600$ , which is in the vortex shedding regime. If wake capture is playing a significant role in particle scavenging it would follow that once the wake becomes unstable during vortex shedding the likelihood of particle capture by this method is reduced significantly, and would lead to the observed decrease in the residual. Furthermore, wake capture of particles is not included in Beard's simulations, and is unlikely to have an effect in Walton and Woolcock's data due to their experimental apparatus, which used a vertical wind tunnel, and, instead of a freely floating drop, a pendent drop. This drop was supported with a fixed structure which would make the wake different from that of a freely falling drop. Because the observed trend approximately



Fig. 3. Relationship between the residual,  $e_{s}$ , and  $Stk_r$  for the unmodified Slinn model,  $E_s$ .



**Fig. 4.** Plots of residual versus *Re*<sub>D</sub> for: (a) the Slinn model and (b) the Calvert model. The data sets are: •, Walton and Woolcock (1960); •, Quérel et al. (2014); •, Chate and Kamra (1997); •, Pranesha and Kamra (1996); △, Leong et al. (1982) and Starr and Mason (1966); and •, Gunn and Hitschfeld (1950).

matches the expected trend for the onset of vortex shedding and because it is reasonable to conclude that this mechanism is not accounted for in either model, it is possible that wake capture plays a role in scavenging in the inertial regime.

#### 6. Conclusion

This work shows that the Calvert model better predicts published experimental scavenging data in the inertial regime. Modifications to the two models are given in Eqs. (15) and (17), both of which better describe the measured results than either unmodified model. Two mechanisms other than inertial impaction were identified as playing a measurable role in scavenging within the inertial regime based upon the parametric study of the model residuals conducted. The dimensionless group  $Stk_r$  indicates an inertial mechanism at play, likely the compression of the particle phase near the front hemisphere of the drop. The dimensionless group  $Re_D$  indicates an advective mechanism at play, perhaps wake dynamics due to the drop off at high  $Re_D$ . Further experimental investigation is required to confirm that these are, in fact, the correct mechanisms described by the identified dimensionless groups.

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